

Getting Started

Creating Applications with µVision®4

関 Blinky - μVision	
<u>Fi</u> le <u>Edit V</u> iew <u>P</u> roject Fl <u>a</u> sh <u>D</u> ebug Peripherals <u>T</u> ools <u>S</u> VCS <u>W</u> indow <u>H</u> elp	
Project • # x Disassembly • # x Logic Analyzer	▲ # ×
98: AD value = ADC_ConvertedValue; 0x08000700_2805 LDR: r0, [po, 446]; 80x08000704 0x08000702_805 LDR: r5, [r0, 45000] 99: AD scaled = AD value / 52; 0x08000706_2805 LDR: r5, [r0, 45000] 99: AD scaled = AD value / 52; 0x08000706_2805 r5, [r0, 45000] 99: AD scaled = AD value / 52; 0x08000714 0x08000706_2805 r5, r7, r5 0x08000714 AD scaled (* AD scaled ex) { 0x08000714 0x08000706_4227 CMP r7, r5 0x08000714 AD scaled (* AD scaled ex) { 0x08000714 0x08000706_4227 CMP r7, r5 0x08000714 AD scaled (* AD scaled) 0x08000714 0x08000707_4528 MOV r6, r7 101: AD scaled (* AD scaled) 0x08000714 0x08000707_4528 MOV r6, r7 103: 101: AD scaled) 0x08000714 0x08000707_4528 MOV r6, r7 100: 150: MIM T MIM T 0x0800070_4528 MOV r6, r7 100: 100: 100: 100: 100: 0x0800070_648 MOV r6, r7 100: 100: 100:	Image: Max Time: Range: Grid: Zoom: 16 ms 2070134 s 2000000 s 0.100000 s In Out 16 ms 2070134 s 2000000 s 0.100000 s In Out 10 ms 0 ms 0 ms 0.0000 s 0.100000 s In Out 10 ms 0 ms 0 ms 0 ms 0 ms In In 11 ms 0 ms 0 ms 0 ms In In 11 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms In In 12 ms 0 ms 0 ms In In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In 12 ms 0 ms 0 ms 0 ms In <
Command V4 X Call Stack V4 X	
Stack Frames Value/Address	Address: 0x10000000
LCD Display()	0x10000000: MCBSTM32 DEMC
Analog (3)	0x10000022: 0x10000044:
Analog (3.000000) entered.	0x10000066:
	0x10000088:
	0x1000000CC:
ASSIGN BreakDisable BreakEnable BreakKill Call Stack Call Stack	0x100000EE:
Simulation	t1: 2.07013396 sec CAP NUM SCE

For 8-bit, 16-bit, and 32-bit Microcontrollers

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NOTE

This manual assumes that you are familiar with Microsoft Windows and the hardware and instruction set of the ARM7, ARM9, Cortex-Mx, C166, XE166, XC2000, or 8051 microcontroller.

Every effort was made to ensure accuracy in this manual and to give appropriate credit to persons, companies, and trademarks referenced herein.

Preface

This manual is an introduction to the Keil development tools designed for Cortex-Mx, ARM7, ARM9, C166, XE166, XC2000, and 8051 microcontrollers. It introduces the μ Vision Integrated Development Environment, Simulator, and Debugger and presents a step-by-step guided tour of the numerous features and capabilities the Keil embedded development tools offer.

Who should Read this Book

This book is useful for students, beginners, advanced and experienced developers alike.

Developers are considered experienced or advanced if they have used μ Vision extensively in the past and knowledge exists of how the μ Vision IDE works and interacts with the debugger, simulator, and target hardware. Preferably, these developers already have a deep understanding of microcontrollers. We encourage this group of engineers to get familiar with the enhancements introduced and to explore the latest features in μ Vision.

Developers are considered students or beginners if they have no working experience with μ Vision. We encourage this group of developers to start by reading the chapters related to the μ Vision IDE and to work through the examples to get familiar with the interface and configuration options described. They should make use of the ample possibilities the simulator offers. Later on, they should continue with the chapters describing the RTOS and microcontroller architectures.

However, it is assumed that you have a basic knowledge of how to use microcontrollers and that you are familiar with a few instructions or with the instruction set of your preferred microcontroller.

The chapters of this book can be studied individually, since they do not strictly depend on each other.