

# RAPID

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For other uses, see [Rapid \(disambiguation\)](#).

RAPID

**Designed by** [ABB Group](#)

**Developer** [ABB Group](#)

**First appeared** 1994

**Influenced by**

[ARLA](#), [C](#)

**RAPID** is a [high-level programming language](#) used to control ABB industrial robots. RAPID was introduced along with S4 Control System in 1994 by [ABB](#), superseding the [ARLA](#) programming language.

Features in the language include:

- Routine parameters:
  - Procedures - used as a subprogram.
  - Functions - return a value of a specific type and are used as an argument of an instruction.
  - Trap routines - a means of responding to interrupts.
- Arithmetic and logical expressions
- Automatic error handling
- Modular programs
- Multi tasking