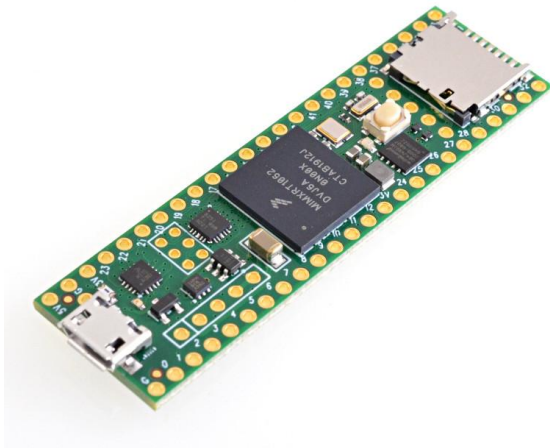




Teensy 4.1 ARM Cortex-M7 Microcontroller Development Board



The Teensy 4.1 is the newest version of the popular Teensy development platform that features an ARM Cortex-M7 processor at 600MHz, with a NXP iMXRT1062 chip, four times larger flash memory than the 4.0, and two new locations to optionally add more memory. The Teensy 4.1 is the same size and shape as the Teensy 3.6 (2.4in by 0.7in), and provides greater I/O capability, including an ethernet PHY, SD card socket, and USB host port.

When running at 600 MHz, the Teensy 4.1 consumes approximately 100mA current and provides support for dynamic clock scaling. Unlike traditional microcontrollers, where changing the clock speed causes wrong baud rates and other issues, Teensy 4.1 hardware and Teensyduino's software support for Arduino timing functions are designed to allow dynamically speed changes. Serial baud rates, audio streaming sample rates, and Arduino functions like `delay()` and `millis()`, and Teensyduino's extensions like `IntervalTimer` and `elapsedMillis`, continue to work properly while the CPU changes speed. Teensy 4.1 also provides a power shut off feature. By connecting a pushbutton to the On/Off pin, the 3.3V power supply can be completely disabled by holding the button for five seconds, and turned back on by a brief button press. If a coin cell is connected to VBAT, Teensy 4.1's RTC also continues to keep track of date & time while the power is off. Teensy 4.1 also can also be overclocked, well beyond 600MHz.

The ARM Cortex-M7 brings many powerful CPU features to a true real-time microcontroller platform. The Cortex-M7 is a dual-issue superscaler processor, meaning the M7 can execute two instructions per clock cycle, at 600MHz! Of course, executing two simultaneously depends upon the compiler ordering instructions and registers. Initial benchmarks have shown C++ code compiled by Arduino tends to achieve two instructions about 40% to 50% of the time while performing numerically intensive work using integers and pointers. The Cortex-M7 is the first ARM microcontroller to use branch prediction. On M4, loops and other code which must take three clock cycles. With M7, after a loop has executed a few times, the branch prediction removes that overhead, allowing the branch instruction to run in only a single clock cycle.

Tightly Coupled Memory is a special feature which allows Cortex-M7 fast single cycle access to memory using a pair of 64 bit wide buses. The ITCM bus provides a 64 bit path to fetch instructions.

The DTCM bus is actually a pair of 32 bit paths, allowing M7 to perform up to two

separate memory accesses in the same cycle. These extremely high speed buses are separate from M7's main AXI bus, which accesses other memory and peripherals. 512 of memory can be accessed as tightly coupled memory. Teensyduino automatically allocates your Arduino sketch code into ITCM and all non-malloc memory use to the fast DTCM, unless you add extra keywords to override the optimized default. Memory not accessed on the tightly coupled buses is optimized for DMA access by peripherals. Because the bulk of M7's memory access is done on the two tightly coupled buses,

powerful DMA-based peripherals have excellent access to the non-TCM memory for highly efficient I/O.

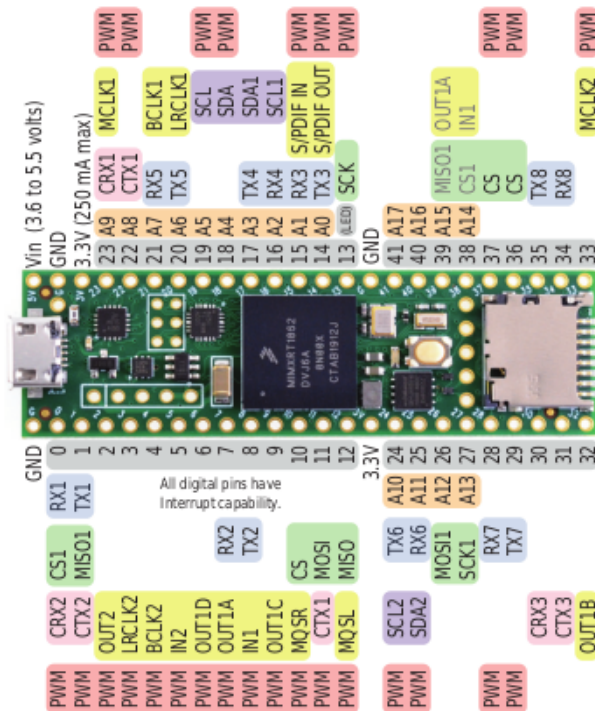
Teensy 4.1's Cortex-M7 processor includes a floating point unit (FPU) which supports both 64 bit "double" and 32 bit "float". With M4's FPU on Teensy 3.5 & 3.6, and also Atmel SAMD51 chips, only 32 bit float is hardware accelerated. Any use of double, double functions like `log()`, `sin()`, `cos()` means slow software implemented math. Teensy 4.1 executes all of these with FPU hardware.

Note: The Teensy 4.1 does not include headers and will need to be purchased separately and soldered on yourself.

Teensy 4.1 Specifications

- ARM Cortex-M7 at 600 MHz
- Float point math unit, 64 & 32 bits
- 7936K Flash, 1024K RAM (512K tightly coupled), 4K EEPROM (emulated)
- QSPI memory expansion, locations for 2 extra RAM or Flash chips
- USB device 480 Mbit/sec & USB host 480 Mbit/sec
- 55 digital input/output pins, 35 PWM output pins
- 18 analog input pins
- 8 serial, 3 SPI, 3 I2C ports
- 2 I2S/TDM and 1 S/PDIF digital audio port
- 3 CAN Bus (1 with CAN FD)
- 1 SDIO (4 bit) native SD Card port
- Ethernet 10/100 Mbit with DP83825 PHY
- 32 general purpose DMA channels
- Cryptographic Acceleration & Random Number Generator
- RTC for date/time
- Programmable FlexIO
- Pixel Processing Pipeline
- Peripheral cross triggering
- Power On/Off management

www.pjrc.com/teensy



On/Off
Program
GND
3.3V
VBAT

Use 3V coin cell for Date & Time & power management

SD Card

47 DAT2
46 DAT3
45 CMD
3.3V
44 CLK
GND
43 DAT0
42 DAT1

TX5
RX5
SCK2
CS2
MOSI2
MISO2

PWM
PWM
PWM
PWM
PWM
PWM

RX8
CS0
D1
D2
GND

SCK2
MOSI2

48
49
50
51
52

CS1
D1
D2
GND

SCK2
MOSI2

PWM
SCL1

3.3V
54
53
52

D3
CLK
D0

MISO2
TX1
RX1

* Rin is shown twice

3.3V
54
53
52

D3
CLK
D0

MISO2
TX1
RX1

5V
D+
D-
GND
GND

USB Host

RX+
LED
TX-
GND
TX+

Ethernet

QSPI Memory

Cut to separate VIN from VUSB, if using external power.

VUSB
D+
D-
GND

USB Device

www.pjrc.com/help

Teensy 4.1 pins are **not 5 volt tolerant**. Do not apply more than 3.3V to any pin, except VIN & VUSB.

PC computer with Windows 7, 8, 10, 11 or later
or Ubuntu Linux 14.04 or later
or Macintosh MacOS 10.10 or later
USB Micro-B Cable

